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S-IVB-502 STAGE TECHNICAL PERFORMANCE CRITERIA DOCUMENT

ORIGINAL ISSUE: DECEMBER 1967 REVISED: 28 MARCH 1968

MISSILE & SPACE SYSTEMS DIVISION

S-IVB-502 STAGE TECHNICAL PERFORMANCE CRITERIA DOCUMENT

DOUGLAS REPORT DAC-56610A ORIGINAL ISSUE: DECEMBER 1967 REVISED 28 MARCH 1968

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PREPARED FOR:
NATIONAL AERONAUTICS AND
SPACE ADMINISTRATION
UNDER NASA CONTRACT NAS7-101

ENGINEERING - SATURN/APOLLO

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| AP2-1 | 28 March 1968 |

ABSTRACT

This Technical Performance Criteria Document contains the AS-502 mission objectives and the S-IVB-502 stage technical performance criteria which will be used to determine the Contractor's cost plus incentive fee bonus or penalty pertaining to mission accomplishment, payload capabilities and telemetry performance.

DESCRIPTORS

CPIF (cost plus incentive fee)
AS-502 Mission
S-IVB-502 stage
Preconditions of Flight
End Conditions of Flight
Telemetry Performance
Payload Capability

PREFACE

This Technical Performance Criteria Document was prepared in accordance with MSFC-DRL-021 Line Item 181 (reference 1) and supporting Data Requirements Description SE-956 (reference 1). The document contains the AS-502 mission objectives and the S-IVB-502 stage technical performance criteria which will be used to determine the Contractor's cost plus incentive bonus or penalty pertaining to mission accomplishment, payload capabilities, and telemetry performance.

PREFACE TO FIRST REVISION

Dated 28 March 1968

This report contains the second issue of the S-IVB-502 Technical Performance Criteria Document and completely supercedes the original report issued in December 1967.

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SECTION 1

INTRODUCTION

1. INTRODUCTION

This Technical Performance Criteria Document was prepared in accordance with MSFC-DRL-021 Line Item 181 (reference 1) and supporting Data Requirements Description SE-956 (reference 1). The document contains the AS-502 mission objectives and the S-IVB-502 stage technical performance criteria which will be used to determine the Contractor's cost plus incentive bonus or penalty pertaining to mission accomplishment, payload capability, and telemetry performance as defined in contract NAS7-101, supplemental agreement 1100.

The technical performance criteria includes the required preconditions of flight, end conditions of flight, mission duration, payload capability, and telemetry performance. The telemetry performance will be evaluated for two phases: (1) liftoff until first S-IVB stage ECC + 10 seconds and (2) liftoff until planned LV/SC separation.

Douglas Aircraft Company considers the SA-502 Launch Vehicle

Mission Directive (reference 2) as the official document for providing identification and control of the launch vehicle mission requirements. These requirements include the primary and secondary mission objectives and are presented in section 2.

SECTION 2

MISSION OBJECTIVES

2. MISSION OBJECTIVES

Douglas Aircraft Company considers the SA-502 Launch Vehicle Mission Directive (reference 2) as the official document for providing identification and control of the launch vehicle mission requirements. Apollo Flight Mission Assignments document (reference 3) and the Program Support Requirements document (reference 4) also define mission objectives and can be referred to for supplemental information. The mission directive states that "primary objectives are those which are mandatory and therefore, malfunctions of launch vehicle systems, ground equipment or instrumentation which would result in failure to achieve those objectives will be cause to hold or cancel the mission until the malfunction has been eliminated." The AS-502 primary objectives, as listed in the mission directive, are shown below with assigned priorities indicated to the right of each objective. For a nominal AS-502 flight, all primary launch vehicle objectives are of equal importance. The assigned priorities are intended for use in realtime mission contingency planning only.

| | Primary Objectives | Assigned Priorities |
|----|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------|
| а. | Demonstrate the S-IVB stage restart capability | 1 |
| Ъ. | Demonstrate the adequacy of the S-IVB continuous vent system while in earth orbit | 2 |
| c. | Demonstrate the capability of the S-IVB auxiliary propulsion system during S-IVB powered flight and orbital coast periods to maintain attitude control and perform required maneuvers | 2 |
| d. | Demonstrate the S-IVB stage propulsion system including the propellant management systems; and determine inflight system performance parameters | 2 |
| e. | Demonstrate the S-II stage propulsion system, including programmed mixture ratio shift and the propellant management system and determine inflight performance parameters | 3 |

| | Primary Objectives | Assigned Priorities |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------|
| f. | Demonstrate the S-IC stage propulsion system, and determine inflight system performance parameters | 4 |
| g. | Demonstrate S-IC/S-II dual plane separation | 5 |
| h. | Demonstrate S-II/S-IVB separation | 5 |
| i. | Demonstrate the mission support capability required for launch and mission operations to high post-injection altitudes | 6 |
| j. | Demonstrate structural and thermal integrity of launch vehicle throughout powered and coasting flight, and determine inflight structural loads and dynamic characteristics | 6 |
| k. | Determine inflight launch vehicle internal environment | 6 |
| 1. | Demonstrate the launch vehicle guidance and control system during S-IC, S-II, and S-IVB powered flight, achieve guidance cutoff and evaluate system accuracy | 6 |
| m. | Demonstrate launch vehicle sequencing system | 6 |
| n. | Evaluate performance of the emergency detection system (EDS) in a closed-loop configuration | 6 |
| 0. | Demonstrate compatibility of the launch vehicle and spacecraft | 6 |
| p. | Verify prelaunch and launch support equipment compatibility with launch vehicle and spacecraft systems. | 7 |

Secondary objectives as defined in the mission directive "are those which are desirable but not mandatory. Malfunctions which may result

in failure to attain these objectives may be cause to hold or cancel the mission as indicated in the launch mission rules." The secondary objectives which are listed in the mission directive are as follows:

- a. Determine launch vehicle powered flight external environment
- b. Determine attenuation effects of exhaust flames on RF radiating and receiving systems during main engine, retro and ullage motor firings.

SECTION 3

TECHNICAL PERFORMANCE CRITERIA

3. TECHNICAL PERFORMANCE CRITERIA

3.1 General

The Douglas Aircraft Company will be awarded a bonus if the S-IVB-502 stage successfully accomplishes the assigned flight mission. Conversely, the Contractor will be assessed a penalty if the S-IVB-502 stage fails to accomplish the assigned flight mission because of inadequate stage performance.

The S-IVB stage requirements are presented in the <u>Contract End Item</u>
Detail Specification, No. CP209000A (reference 5).

3.2 Flight Mission Accomplishment

A mission is considered to be successfully accomplished if the S-IVB-502 stage delivers to the payload acceptable valued End Conditions of Flight (ECF) or, if having received from the lower stages and/or instrument unit (IU) inadequate Preconditions of Flight (PCF), the S-IVB stage performance is such that the ECF would have been accomplished had the PCF been adequate.

Tables 3-1 and 3-2 present the Douglas position on PCF, ECF, and their respective allowable tolerances applicable to its S-IVB-502 flight mission.

The flight time which will be used in calculating and evaluating the PCF parameters will be the time when the IU will have issued the S-II/S-IVB separation command. The flight time which will be used in calculating and evaluating the ECF trajectory parameters will be the time when the S-IVB-502 stage will have been injected into the waiting orbit, which is defined as 10 sec after the IU command signal is issued for second S-IVB J-2 engine cutoff.

The ECF attitude control parameters will be evaluated throughout S-IVB flight until S-IVB/CSM separation signal. Tolerances have been established for three specific flight phases; S-IVB powered

flight, parking orbit, and waiting orbit. In the assessment of attitude control ECF, a temporary or intermittent out of tolerance condition shall not be considered an ECF violation unless the condition is caused by an S-IVB system or subsystem failure.

Table 3-3 presents the definitions used with the PCF and ECF parameters. Table 3-4 presents the equations used for calculation of ECF parameters.

3.3 Payload Capability

Payload capability for the S-IVB-502 stage is not incentivised.

3.4 Telemetry Performance Evaluation

The measurements to be evaluated for technical performance incentives are those listed in the <u>Instrumentation Program and Components List</u> (IP&CL) (reference 6) that are wholly on the S-IVB-502 stage and which are operative at the time the automatic launch sequence is initiated.

Measurements which achieve their intended purpose are scored as successful. Measurements which do not obtain valid data due to noise from unknown sources will be removed from the total number of measurements upon which the telemetry performance evaluation is based.

The IP&CL lists a total of 618 measurements of which 12 are not active during flight and 4 are not wholly on the S-IVB stage, leaving a total of 602 measurements to be evaluated for technical performance incentives.

The inactive measurements that will not be evaluated are listed in the following table:

| Measurement No. | Measurement | Reason |
|--------------------|---------------------------------------|-------------------------------------|
| K0141-411 | Event - R/S 1 Pulse Sensor | These measurements |
| K0142-411 | Event - R/S 2 Pulse Sensor | are for checkout |
| K0149-404 | Event - U/R Jettison l Pulse Sensor | only and are not transmitted during |
| K0150-404 | Event - U/R Jettison 2 Pulse Sensor | flight by the |
| K0168-404 | Event - Switch Selector Register Test | S-IVB-502 stage T/M system. |

| K0169-404 K0176-404 K0177-404 | Event - EBW Pulse Sensor OFF Indication Event - Ullage Rocket Ignition Pulse Sensor 1 Indication Event - Ullage Rocket Ignition Pulse Sensor 2 Indication | flight by the |
|-------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| D0545-407 D0576-408 D0577-406 | Press - Common Bulkhead Int-H/W Press - Fuel Tank Ullage Umb-H/W Press - Oxid Tank Ullage Umb-H/W | These measurements are landline for prelaunch requirements and are not transmitted during flight by the S-IVB-502 stage T/M system. |
| K0152-404 | Event - Rate Gyro Wheel Speed OK Indications | Rate Gyro is not installed. |

The measurements not wholly on the S-IVB stage are the following:

| D0153-423 | Press - Chamb | Retro Rkt | Pos IV-I | |
|-----------|---------------|-----------|------------|---------------------|
| D0154-421 | Press - Chamb | Retro Rkt | Pos II-III | Transmitted by S-II |
| D0155-420 | Press - Chamb | Retro Rkt | Pos I-II | stage T/M |
| D0156-422 | Press - Chamb | Retro Rkt | Pos III-IV | |

3.4.1 Performance Baseline Determination

Douglas Aircraft Company will utilize the following procedure to establish the operative and non-operative telemetry measurements at the initiation of the last automatic sequence prior to liftoff. This information will be used as the baseline for subsequent calculation of the telemetry performance incentive.

Prior to resuming the count for T -0 day, the DAC/FTC Project Engineer will contact MSFC/S-IVB Project Office to review the inoperative measurements, their failure mode, and their effect on launch and/or mission.

Continual surveillance for inoperative measurements will be made by Contractor personnel in the blockhouse and the Central Instrumentation Facility (CIF) during T -0 day. MSFC will be periodically contacted by the DAC/FTC Project Engineer up until approximately T -15 min to report

any additional inoperative measurements detected either by the Launch Control Center or CIF personnel. Measurement scans will be made periodically by dialing up measurements in the CIF and the Saturn V Measuring Station. MSFC will in most instances be able to verify inoperative measurements by viewing the same data as it is being transmitted to the Huntsville Operations Support Center (HOSC) from the CIF.

The Douglas S-IVB Project Engineer will dictate a Memo of Agreement to document those measurements which the Contractor declares inoperative prior to initiation of the automatic launch sequence.

3.4.2 Performance Evaluation Period

The expected duration of the telemetry performance evaluation will be as follows:

a. Phase I

From AS-502 launch vehicle liftoff until first S-IVB stage ECC +10 sec.

b. Phase II

From AS-502 launch vehicle liftoff until planned LV/SC separation, as defined in the <u>Definition of Saturn SA-502 Flight</u>
Sequence Program, No. 40M33622 (reference 7).

PCM transmitter ON

3.4.3 Command Requirements

Special calibration relays ON

In order to ensure the required transmission of data from the S-IVB stage telemetry system, the following commands must be received from the IU as scheduled in the sequence of events:

Special calibration relays OFF PCM transmitter OFF

Regular calibration relays ON Slow record ON

Regular calibration relays OFF Slow record OFF

FM transmitters ON Fast record ON

FM transmitters OFF Fast record OFF

FM SCO assemblies ON Recorder playback ON

FM SCO assemblies OFF Recorder playback OFF

SSB/FM transmitter ON Emergency playback ON

Emergency playback OFF

SSB/FM transmitter OFF

TABLE 3-1 (Sheet 1 of 2)
DOUGLAS POSITION, S-IVB-502 PCF AND ASSOCIATED TOLERANCES
(S-II/S-IVB SEPARATION COMMAND)

| | QAT_C/TT_C) | (3-11/3-1VB SEFANALION CONTINUE) | riend) | | |
|-----------------------------------------------------------------|-------------|----------------------------------|----------------|----------------------------|-------------------|
| PARAMETERS | UNITS | NOMINAL | TOLERANCES | EVALUATION** INACCURACY | TOTAL ENVELOPE |
| *Range | km | +1,505.4 | +54.6 -70.3 | +0.8 | +55.4 |
| *Crossrange (see note 1) | k'm | +40.8 | +2.7 | 8.0+1 | +3.5 |
| *Altitude | km | +188.8 | +2.6 | 8 • • • | +3.4 |
| Velocity Vector Magnitude | m/sec | +6,834.4 | +49.4 | 1+3.0 | +52.4 |
| Velocity Vector Direction (Path Angle from Local Horizontal) | deg | +0.78 | +0.33 | +0.05 | +0.38 |
| Pitch Attitude (see note 2) | deg | -96.3 | +4.0 -4.0 | +1.0 | +5.0 |
| Pitch Rate | deg/sec | 0.0 | +1.0 | +0.5 | +1.5 |
| Yaw Attitude (see note 3) | deg | +0.3 | +2.8 | +1.0 | +3.8 |
| Yaw Rate | deg/sec | 0.0 | +1.0 | +0.5 | +1.5 |
| Roll Attitude | deg | 0.0 | +3.0 | 11.0 | +4.0 -4.0 |
| Roll Rate | deg/sec | 0.0 | +1.0 | +0.5 | +1.5 |

TABLE 3-1 (Sheet 2 of 2)
DOUGLAS POSITION, S-IVB-502 PCF AND ASSOCIATED TOLERANCES
(S-II/S-IVB SEPARATION COMMAND)

*Earth fixed.

**Assuming only radar tracking available for trajectory parameters.

NOTES:

- Crossrange is measured laterally, along a line normal to the plane containing the flight Positive is to the right, azimuth, the launch pad plumbline, and the earth center. looking along the azimuth direction.
- Pitch attitude is measured negatively nose downrange from the launch vertical, in the pitch plane. 5
- Yaw attitude is measured positive nose to the right in the yaw plane, as seen looking forward with position one down. .

TABLE 3-2 (Sheet 1 of 2)
DOUGLAS POSITION, S-IVB-502 ECF AND ASSOCIATED TOLERANCES
(WAITING ORBIT INJECTION)

A. S-IVB TRAJECTORY ECF PARAMETERS

| PARAMETERS | UNITS | NOMINAL | TOLERANCES | LH2 UNCERTAINTY | EVALUATION* INACCURACY | TOTAL |
|--------------|----------------------------------|------------|--------------------|-----------------|---------------------------|----------------------|
| Inclination | deg | +32,485 | +0.033 | +0.000 | +0.016 | +0.049 |
| Node | deg | +122.490 | +0.190 | +0.000 | +0.030 | +0.220 |
| °2 | m ² /sec ² | -1,491,156 | +32,661 -31,356 | +7,664 | +85,350 | +125,675 -193,679 |
| Eccentricity | - | +0.97532 | +0.00054 | +0.00012 | +0.00140 | +0.00206 |

B. S-IVB ECF ATTITUDE CONTROL PARAMETERS**

| PARAMETERS | UNITS | TOLERANCES | EVALUATION | TOTAL |
|-----------------------------|---------|---------------|------------|---------------|
| | | | INACCURACY | ENVELOPE |
| S-IVB Burn Phase | | | | |
| Pitch or Yaw Attitude Error | deg | +5.0 | +1.0 | 0.9+1 |
| Roll Attitude Error | deg | <u>+</u> 12.5 | +1.0 | <u>+</u> 13.5 |
| Pitch or Yaw Rate | deg/sec | +2.5 | +0.5 | +3.0 |
| Roll Rate | deg/sec | +1.0 | +0.5 | <u>+</u> 1.5 |
| | | | - | |

TABLE 3-2 (Sheet 2 of 2)
DOUGLAS POSITION, S-IVB-502 ECF AND ASSOCIATED TOLERANCES
(WAITING ORBIT INJECTION)

| | | / | | |
|------------------------------------------|---------|------------|--------------------------|-------------------|
| PARAMETERS | UNITS | TOLERANCES | EVALUATION INACCURACY | TOTAL ENVELOPE |
| Parking Orbit (to restart) | | | | |
| Pitch or Yaw Attitude Error | deg | 1+3.0 | +1.0 | ++4.0 |
| Roll Attitude Error | deg | +12.5 | +1.0 | +13.5 |
| Pitch or Yaw Rate | deg/sec | +0.7 | +0.5 | +1.2 |
| Roll Rate | ges/sec | +1.0 | + 0.5 | <u>+</u> 1.5 |
| Waiting Orbit (to CSM separation signal) | | | | |
| Pitch or Yaw Attitude Error | deg | +3.0 | +1.0 | 1+4.0 |
| Roll Attitude Error | deg | +12.5 | +1.0 | +13.5 |
| Pitch or Yaw Rate | deg/sec | +1.6 | +0.5 | +2.1 |
| Roll Rate | deg/sec | +1.6 | 1+0.5 | +2.1 |
| | | | | |

*Assuming only radar tracking available for trajectory parameters.

**Attitude errors during parking and waiting orbit exclude normal transients and maneuvers; all rates apply to rigid body response (structural dynamics effects are excluded).

TABLE 3-3 (Sheet 1 of 2) PCF AND ECF PARAMETER DEFINITION

| PARAMETER | DEFINITION |
|------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Range | Spherical earth ground range. Based on the spherical earth range angle and the average earth radius. |
| Cross-range | Component of vehicle position as measured laterally, along a line normal to the plane containing the flight azimuth, the launch pad plumbline, and the earth center. Positive is to the right, looking along the azimuth direction. |
| Altitude | Distance between the spheroid's surface and vehicle measured along the normal to the earth's surface, positive up. |
| Velocity vector magnitude | Measured with respect to non-rotating space fixed reference system. |
| Velocity vector direction | Angle between inertial velocity vector and a plane perpendicular to the instantaneous earth radius vector. |
| Pitch attitude | Inertial Euler angle measured between the platform "P" coordinate system and the vehicle fixed "M" system. The rotation order is pitch, yaw, roll. Pitch attitude is measured negatively nose downrange from the launch vertical, in the pitch plane. |
| Pitch rate | Angular velocity about vehicle pitch axis, positive nose up. |
| Pitch attitude error | Commanded pitch attitude minus the vehicle pitch attitude measured in vehicle coordinates. |
| Yaw attitude | Inertial Euler angle measured between the platform "P" coordinate system, and the vehicle fixed "M" system. The rotation order is pitch, yaw, roll. Yaw attitude is measured positive nose to the right in the yaw plane, as seen looking forward with position one down. |
| Yaw rate | Angular velocity about vehicle yaw axis, positive nose right. |

TABLE 3-3 (Sheet 2 of 2) PCF AND ECF PARAMETER DEFINITION

| PARAMETER | DEFINITION |
|----------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Yaw attitude error | Commanded yaw attitude minus the vehicle yaw attitude measured in vehicle coordinates. |
| Roll attitude | Inertial Euler angle measured between the platform "P" coordinate system and the vehicle fixed "M" system. The rotation order is pitch, yaw, roll. Roll attitude is measured positive in the roll plane in a clockwise direction as seen looking forward. |
| Roll rate | Angular velocity about vehicle roll axis, positive clockwise looking forward. |
| Roll attitude error | Commanded roll attitude minus the vehicle roll attitude measured in vehicle coordinates. |
| Inclination (i) Eccentricity (e) Longitude of Descending Node (θ_N) | Elements of waiting orbit. Longitude of descending node is measured in the earth's equatorial plane relative to the longitude of the launch site at Guidance Reference Release, positive east. Calculated as shown in table 3-4. |
| Energy (C ₃) | Energy of waiting orbit. Equals twice the total waiting orbit vis-viva energy. Calculated as shown in table 3-4. |

TABLE 3-4 EQUATIONS FOR C₃, INCLINATION, NODE PARAMETER AND ECCENTRICITY

The equations used to calculate eccentricity, C_3 , node, and inclination for the AS-502 S-IVB ECF's are listed below. Position and velocity data used to calculate the sub-equations of P and γ are in the Apollo Coordinate System Standard 13.

Eccentricity =
$$\sqrt{1 - \frac{(2\mu - RV^2) (1 - \sin^2 \gamma) RV^2}{\mu^2}}$$

 $C_3 = V^2 - \frac{2\mu}{R}$
Node = $\cos^{-1} - \left(\frac{P_u}{P_{uv}}\right) = 90^\circ + \sin^{-1}\left(\frac{P_u}{P_{uv}}\right)$
Inclination = $\cos^{-1}\left(\frac{P_w}{P}\right)$
Using $\bar{P} = \bar{V} \times \bar{R}$
 $P_u = P_3 \sin A_z + P_2 \cos A_z$
 $P_v = -P_3 \sin \phi_L \cos A_z + P_1 \cos \phi_L + P_2 \sin \phi_L \sin A_z$
 $P_w = -P_3 \cos \phi_L \cos A_z - P_1 \sin \phi_L + P_2 \cos \phi_L \sin A_z$
 $P_{uv} = \sqrt{P_u^2 + P_v^2}$
 $\gamma = \sin^{-1}\left(\frac{x\dot{x} + y\dot{y} + z\dot{z}}{RV}\right)$
 $\mu = 3.986032E14 m^3/sec^2$
 $A_z = 72 deg$

 $\phi_{T} = 28.60842 \text{ deg}$

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| | | | | | APPENDIX 1 |
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| | | , | | GLOSSARY AND A | BBREVIATIONS |
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TABLE AP 1-1 (Sheet 1 of 2) GLOSSARY AND ABBREVIATIONS

| ABBREVIATION | TERM | DEFINITION |
|--------------|------|--------------------------------------------------|
| AS | | Apollo Saturn |
| CPIF | | Cost plus incentive fee |
| CIF | | Central Instrumentation Facility |
| CSM | | Command service module |
| DAC | | Douglas Aircraft Company |
| DAC/FTC | | Douglas Aircraft Company, Florida Test Center |
| deg | | Degree |
| EBW | | Exploding bridgewire |
| ECC | | Engine Cutoff Command |
| ECF | | End Conditions of Flight |
| EDS | | Emergency Detection System |
| FM | | Frequency modulation |
| HOSC | | Huntsville Operations Support Center |
| H/W | | Hardwire |
| IP&CL | | Instrument Program and Components List |
| IU | | Instrument Unit |
| km | | Kilometers |
| LV | | Launch vehicle |
| MSFC | | Marshall Space Flight Center |
| NASA | | National Aeronautics and Space Administration |
| PCF | | Preconditions of Flight |
| PCM | · | Pulse code modulation |

TABLE AP 1-1 (Sheet 2 of 2) GLOSSARY AND ABBREVIATIONS

| ABBREVIATION | TERM | DEFINITION |
|--------------|------------|-----------------------------------------------------------------------------------------------------------------|
| RF | | Radio frequency |
| R/S | | Range safety |
| SA | | Saturn |
| SC | Spacecraft | Includes Apollo command and service module and LM adapter |
| SCO | | Sub-carrier oscillator |
| S-II | | Second stage of the Saturn V (500) series of vehicles |
| S-IC | | First stage of the Saturn V (500) series of vehicles |
| S-IVB | | Second stage of the Saturn IB (200) series of vehicles and third stage of the Saturn V (500) series of vehicles |
| SSB | | Single sideband |
| T/M | | Telemetry |
| U/R | | Ullage rocket |

APPENDIX 2 REFERENCES

2. REFERENCES

The following listed documents are referenced in the text:

- (1) NAS7-101 Contract Data Requirements Saturn S-IVB Stage and GSE, (MSFC-DRL-021) Line Item 181, Revision A, dated February 1, 1968.
- (2) SA-502 Launch Vehicle Mission Directive, (prepared by Saturn V Test Office), Marshall Space Flight Center, Huntsville, Alabama, Revision A, Change I, dated December 27, 1967.
- (3) Apollo Flight Mission Assignments (U), (prepared by Office of Manned Space Flight, Apollo Program), M-D MA500-11, SE010-000-1, Washington, D.C., dated January, 1968.
- (4) Apollo Saturn V Program Support Requirements, (prepared by Office of Manned Space Flight, Apollo Program), Z1NPX, Revision 2, Washington, D.C., dated December 28, 1967.
- Contract End Item Detail Specification (Prime Equipment)

 Performance Design Requirements, CEI No. 209000A, S-IVB Stages
 501 through 506, Douglas Aircraft Company, Huntington Beach,
 California, dated March 9, 1967.
- (6) Instrumentation Program and Components List S-IVB-502, 1843567AL, Douglas Aircraft Company, Huntington Beach, California, Revision AL, dated February 21, 1968.
- (7) Definition of Saturn SA-502 Flight Sequence Program, Interface Control Document No. 40M33622C (prepared by Airborne Electrical Systems Branch, Astrionics Laboratory) Marshall Space Flight Center, Huntsville, Alabama, dated May 13, 1966.

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KDOO
        Section Chief - Electronics TP&E
KDBA
        Branch Chief - Electronic Stage Design
KDCA
L110
        Chief - Engine Data Reduction Engineering
        Branch Chief - Computing Engineering
KECO
        Branch Chief - Reliability Engineering (2)
KADO
KKBO
        Project Engineer - Test
KKBL
        Assistant Project Engineer - Operations Support
KKBO
        Assistant Project Engineer - Test
5284
        Library
KEBG
        Records
```

S-IVB TP&E COMMITTEE MEMBERS (A3)

| KBDB | Structural Mechanical |
|------|---------------------------------|
| KCBC | Propulsion Performance and TP&E |
| KDBA | Electronics (10) |
| LCCO | Computing Engineering |
| KKBH | TP&E - Flight Test |
| KKBJ | TP&E - Measurements |
| KCBA | Propulsion - System Integration |
| KCBA | Propulsion - Test Requirements |
| KACA | FD&C |
| | |

PROPELLANT UTILIZATION PANEL (A3)

KDCA PU Panel - Electronics

DISTRIBUTION LIST (Continued)

FLORIDA TEST CENTER (A41)

HEOO M. F. Cooper

KKGO F. D. Comer

KAOC J. F. Ryan (2)

KBDE G. C. Norvell (3)

KCDD P. A. Kremer

KDDD L. H. Dybevick (3)

KDDD D. W. Tutwiler

KKGO J. R. Shaffer (3)

KLBO W. D. Guest

SACRAMENTO TEST CENTER (A45)

KKHO E. R. Jacobs (2)

MANNED SPACECRAFT CENTER (A3850)

KO10 K. L. Patelski

MARSHALL SPACE FLIGHT CENTER (A61)

KBDB W. E. Naynola (8)

NASA/MARSHALL SPACE FLIGHT CENTER

H. S. Garret (18)